

Digital Current Transducer HO-NPW series I_{PN} = 80 ... 150 A

Ref: HO 80-NPW; HO 120-NPW; HO 150-NPW

Bitstream output from on onboard Sigma Delta modulator. For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





Features

- Open loop multi-range current transducer
- Bitstream output from 2nd order Sigma-Delta modulator, (PDM) Pulse Density Modulation
- Single supply +5 V
- Overcurrent detect 2.97 × I_{PN} (peak value)
- EEPROM Control
- Galvanic separation between primary and secondary circuit
- Low power consumption
- · Compact design for THT PCB mounting
- Factory calibrated
- Dedicated parameter settings available on request (see page 15).

Advantages

- Low offset drift
- Creepage / clearance 8 mm
- Fast response.

Applications

- AC variable speed and servo motor drives
- · Static converters for DC motor drives
- · Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Combiner box
- Solar inverter on DC side of the inverter (MPPT).

Standards

- IEC 61800-2: 2015
- IEC 61800-3: 2017
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- UL 508: 2013.

Application Domain

• Industrial.

 $N^{\circ}\ 97.P8.31.000.0;\ N^{\circ}\ 97.P8.31.001.0;\ N^{\circ}\ 97.P8.31.002.0;\ N^{\circ}\ 97.P8.31.003.0;\ N^{\circ}\ 97.P8.31.004.0;\ N^{\circ}\ 97.P8.31.005.0;\ N^{\circ}\ 97.P8.31.006.0;\ N^{\circ$

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Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (not destructive)	$U_{\mathrm{C max}}$	V	8
Maximum supply voltage (not entering non standard modes)	$U_{\mathrm{C}\mathrm{max}}$	V	6.5
Maximum primary conductor temperature	$T_{\mathrm{B\;max}}$	°C	120
ESD rating, Human Body Model (HBM)	U_{ESD}	kV	2

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 5

Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT Edition 12
- UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT Edition 17

Ratings

Parameter	Symbol	Unit	Value
Primary involved potential		V AC/DC	600
Max surrounding air temperature	T_{A}	°C	105
Primary current	I_{P}	А	According to series primary current
Secondary supply voltage	$U_{\mathtt{C}}$	V DC	5
Output voltage	$U_{ m out}$	V	0 to 5

Conditions of acceptability

- 1 These devices have been evaluated for overvoltage category III and for use in pollution degree 2 environment.
- 2 A suitable enclosure shall be provided in the end-use application.
- 3 The terminals have not been evaluated for field wiring.
- 5 Primary terminals shall not be straightened since assembly of housing case depends upon bending of the terminals.
- 6 Any surface of polymeric housing have not been evaluated as insulating barrier.
- 7 Low voltage control circuit shall be supplied by an isolating source (such as a transformer, optical isolator, limiting impedance or electro-mechanical relay).

Marking

Only those products bearing the UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.



Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_{d}	kV	4.3	
Impulse withstand voltage 1.2/50 μs	U_{Ni}	kV	8	
Partial discharge RMS test voltage (q _m < 10 pC)	U_{t}	V	1500	Primary/Secondary
Clearance (pri sec.)	$d_{\mathtt{Cl}}$	mm	> 8	Shortest distance through air
Creepage distance (pri sec.)	d_{CP}	mm	> 8	Shortest path along device body
Clearance (pri sec.)	d_{Cl}	mm	> 8	When mounted on PCB with recommended layout
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	
Application example		V	600	Reinforced insulation, according to IEC 61800-5-1, CAT III PD2
Application example		V	1000	Basic insulation, according to IEC 61800-5-1, CAT III PD2

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	T_{A}	°C	-40		105	
Ambient storage temperature	T_{Ast}	°C	-40		105	
Mass	m	g		31		



Electrical data HO 80-NPW

HO 80 ... 150-NPW series

At T_A = 25 °C, U_C = +5 V, unloaded, unless otherwise noted (see Min, Max, typ. definition paragraph in page 17).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal RMS current	$I_{\sf PN}$	А		80		
Primary current, measuring range	I_{PM}	А	-200		200	
Number of primary turns	N_{P}	-		1, 2, 4		See application information
Primary jumper resistance @ 25 °C	$R_{\rm p}$	mΩ		0.09		4 jumpers in parallel
Primary jumper resistance @ 120 °C	R_{P}	mΩ		0.12		4 jumpers in parallel
Supply voltage 1)	U_{C}	V	4.5	5	5.5	
Current consumption	I_{C}	mA		24	31	Unloaded and output mode = 0 2)
Density of ones @ I _P = 0 A	D_{out}	%		50		
Density of ones @ ±I _{PN}	D_{out}	%		50 ±16		
Density of ones @ ±I _{PM}	D_{out}	%		50 ±40		
Allowed load capacitance	C_{L}	pF	0		30	
OCD output on resistance	$R_{ m on\;OCD}$	Ω	60	95	170	Open drain, active low Over operating temperature range
OCD detection hold time	t _{hold OCD}	ms	0.8	1.2	1.7	Additional time after threshold has released
EEPROM control	D_{out}	%		0		Forced to 0 when EEPROM in an error state
Electrical offset for PDM output (@ $I_P = 0$ A)	D_{OE}	%	-0.1		0.1	Relative to D _{out} = 50 %
Electrical offset current referred to primary	I _{OE}	А	-0.5		0.5	
Temperature coefficient of I_{OE} @ $I_{P} = 0$ A	TCI _{OE}	mA/K	-7		7	−40 °C 105 °C
Nominal sensitivity	S_{N}	%/A		0.2		16 % @ I _{PN}
Sensitivity error @ I _{PN}	€ _S	%	-0.75		0.75	Factory adjustment, 1 turn configuration, 4 jumpers in parallel
Temperature coefficient of S	TCS	ppm/K	-250		250	−40 °C 105 °C
Linearity error 0 I_{PN}	ε_{L}	% of I_{PN}	-0.5		0.5	
Linearity error 0 I_{PM}	ε_{L}	% of I _{PM}	-0.5		0.5	
Magnetic offset current (@ $10 \times I_{PN}$) referred to primary	$I_{ m OM}$	А	-0.8		0.8	One turn
Delay time to @ 90 % of the final output value for I_{PN} step	t _{D 90}	μs				Determined by digital filter and OSR ³⁾
Primary current, detection threshold	$I_{ m PTh}$	А	2.67 × I _{PN}	2.97 × I _{PN}	3.27 × I _{PN}	Peak value ±10 %, overcurrent detection (OCD)
Sum of sensitivity and linearity $@I_{PN}$	$\varepsilon_{S^{L}}$	% of I _{PN}	-1.25		1.25	
Sum of sensitivity and linearity (I_{PN}) (I_{PN}) (I_{PN}) (I_{PN}) (I_{PN})	$\varepsilon_{S^{L}}$	% of I_{PN}	-3.95		3.95	See formula note 40
Sum of sensitivity and linearity @ I_{PN} @ T_A = +85 °C	ε_{S} L	% of I _{PN}	-3.28		3.28	See formula note 4)

Notes: 1) 3.3 V SP version available

²⁾ See page 12

³⁾ See page 14
⁴⁾
$$\varepsilon_{S L}(T_{A}) = \varepsilon_{S L 25} + \left(TCS + \frac{TCI_{O E}}{I_{P N}}\right) \times |T_{A} - 25|$$

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Electrical data HO 120-NPW

HO 80 ... 150-NPW series

At T_A = 25 °C, U_C = +5 V, unloaded, unless otherwise noted (see Min, Max, typ. definition paragraph in page 17).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal RMS current	I _{PN}	А		120		
Primary current, measuring range	I_{PM}	Α	-300		300	
Number of primary turns	N_{P}	-		1. 2. 4		See application information
Primary jumper resistance @ 25 °C	$R_{\rm p}$	mΩ		0.09		4 jumpers in parallel
Primary jumper resistance @ 120 °C	R_{P}	mΩ		0.12		4 jumpers in parallel
Supply voltage 1)	U_{c}	V	4.5	5	5.5	
Current consumption	I_{C}	mA		24	31	Unloaded and output mode = 0 ²⁾
Density of ones @ I _P = 0 A	D_{out}	%		50		
Density of ones @ ±I _{PN}	D_{out}	%		50 ±16		
Density of ones @ ±I _{PM}	D_{out}	%		50 ±40		
Allowed load capacitance	C_{L}	pF	0		30	
OCD output on resistance	$R_{ m on\;OCD}$	Ω	60	95	170	Open drain, active low Over operating temperature range
OCD detection hold time	t _{hold OCD}	ms	0.8	1.2	1.7	Additional time after threshold has released
EEPROM control	D_{out}	%		0		Forced to 0 when EEPROM in an error state
Electrical offset for PDM output (@ $I_p = 0$ A)	D_{OE}	%	-0.1		0.1	Relative to D _{out} = 50 %
Electrical offset current referred to primary	I _{OE}	А	-0.75		0.75	
Temperature coefficient of I_{OE} @ $I_{P} = 0$ A	TCI _{OE}	mA/K	-10.5		10.5	−40 °C 105 °C
Nominal sensitivity	S_{N}	%/A		0.1333		16 % @ I _{P N}
Sensitivity error @ I _{PN}	€ _S	%	-0.75		0.75	Factory adjustment, 1 turn configuration, 4 jumpers in parallel
Temperature coefficient of S	TCS	ppm/K	-250		250	−40 °C 105 °C
Linearity error 0 I_{PN}	ε_{L}	% of I_{PN}	-0.5		0.5	
Linearity error 0 $I_{_{\rm PM}}$	ε_{L}	% of $I_{_{\rm PM}}$	-0.5		0.5	
Magnetic offset current (@ $10 \times I_{PN}$) referred to primary	$I_{ m OM}$	А	-0.8		0.8	One turn
Delay time to @ 90 % of the final output value for I_{PN} step	t _{D 90}	μs				Determined by digital filter and OSR 3)
Primary current, detection threshold	$I_{ m PTh}$	А	2.67 × I _{PN}	2.97 × I _{PN}	3.27 × I _{PN}	Peak value ±10 %, overcurrent detection (OCD)
Sum of sensitivity and linearity $@I_{PN}$	ε_{S} L	% of I_{PN}	-1.25		1.25	
Sum of sensitivity and linearity @ I_{PN} @ T_A = +105 °C	ε_{S} L	% of I_{PN}	-3.95		3.95	See formula note ()
Sum of sensitivity and linearity @ I_{PN} @ T_A = +85 °C	ε_{S} L	% of <i>I</i> _{PN}	-3.28		3.28	See formula note 4)

Notes: 1) 3.3 V SP version available

²⁾ See page 12

$$\varepsilon_{S L} (T_{A}) = \varepsilon_{S L 25} + \left(TCS + \frac{TCI_{O E}}{I_{P N}} \right) \times |T_{A} - 25|$$

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Electrical data HO 150-NPW

HO 80 ... 150-NPW series

At T_A = 25 °C, U_C = +5 V, unloaded, unless otherwise noted (see Min, Max, typ. definition paragraph in page 17).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal RMS current	I_{PN}	Α		150		
Primary current, measuring range 85 °C 1) 105 °C	I_{PM}	А	-375 -350		375 350	
Number of primary turns	N_{P}	-		1, 2, 4		See application information
Primary jumper resistance @ 25 °C	R_{P}	mΩ		0.09		4 jumpers in parallel
Primary jumper resistance @ 120 °C	R_{P}	mΩ		0.12		4 jumpers in parallel
Supply voltage 2)	U_{c}	V	4.5	5	5.5	
Current consumption	I_{C}	mA		24	31	Unloaded and output mode = 0 3)
Density of ones @ $I_P = 0$ A	D_{out}	%		50		
Density of ones @ ±I _{PN}	D_{out}	%		50 ±16		
Density of ones @ $\pm I_{_{\rm PM}}$	D_{out}	%		50 ±40		
Allowed load capacitance	C_{L}	pF	0		30	
OCD output on resistance	R _{on OCD}	Ω	60	95	170	Open drain, active low Over operating temperature range
OCD detection hold time	t _{hold OCD}	ms	0.8	1.2	1.7	Additional time after threshold has released
EEPROM control	D_{out}	%		0		Forced to 0 when EEPROM in an error state
Electrical offset for PDM output (@ I_p = 0 A)	D_{OE}	%	-0.1		0.1	Relative to $D_{\text{out}} = 50 \%$
Electrical offset current referred to primary	$I_{\rm OE}$	А	-0.94		0.94	
Temperature coefficient of I_{OE} @ I_{P} = 0 A	TCI _{OE}	mA/K	-13.1		13.1	−40 °C 105 °C
Nominal sensitivity	S_{N}	%/A		0.1067		16 % @ I _{PN}
Sensitivity error @ I_{PN}	$\epsilon_{_{ m S}}$	%	-0.75		0.75	Factory adjustment, 1 turn configuration, 4 jumpers in parallel
Temperature coefficient of S	TCS	ppm/K	-250		250	−40 °C 105 °C
Linearity error 0 I_{PN}	$arepsilon_{L}$	% of I_{PN}	-0.5		0.5	
Linearity error 0 I _{PM}	$arepsilon_{L}$	% of $I_{_{\rm PM}}$	-0.5		0.5	
Magnetic offset current (@ 10 × I_{PN}) referred to primary	I_{OM}	А	-0.8		0.8	One turn
Delay time to @ 90 % of the final output value for I_{PN} step	t _{D 90}	μs				Determined by digital filter and OSR 4)
Primary current, detection threshold	$I_{ m PTh}$	А	2.67 × I _{PN}	2.97 × I _{PN}	3.27 × I _{PN}	Peak value ±10 %, overcurrent detection (OCD)
Sum of sensitivity and linearity @ I _{PN}	$\varepsilon_{S L}$	% of I_{PN}	-1.25		1.25	
Sum of sensitivity and linearity $(D_{PN}) T_A = +105 ^{\circ} C$	$\varepsilon_{S L}$	% of <i>I</i> _{PN}	-3.95		3.95	See formula note 5)
Sum of sensitivity and linearity $(I_{PN} \otimes I_{PN})$ $T_{A} = +85 ^{\circ}$ C	$\varepsilon_{S L}$	% of <i>I</i> _{PN}	-3.28		3.28	OCC IOITIGIA HOLE

Notes: ¹⁾ Magnetic core temperature remaining equal or less than ambiant temperature T_{A} ; ²⁾ 3.3 V SP version available ³⁾ See page 12 ⁴⁾ See page 14

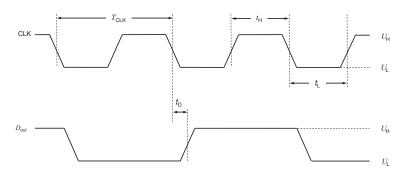
$$\varepsilon_{SL}(T_{A}) = \varepsilon_{SL25} + \left(TCS + \frac{TCI_{OE}}{I_{PN}}\right) \times |T_{A} - 25|$$

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HO-NPW series output characteristics

Mode 0 and 8: 2 Wire CMOS



For all allowed capacitive range

• Timing for mode 0

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock period	T_{CLK}	ns	89	93.5	98	For internal clock
Temperature coefficient of clock period	$TCt_{per\;CLK}$	ppm/K	-400	0	400	−40 °C 105 °C
Clock high time	t _{CLK H}	ns	0.45 × T _{CLK}	46.75	0.55 × T _{CLK}	
Clock falling edge to data delay	t _{CLK D}	ns	-25	0	25	

• Timing for mode 8

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock high time	t _{CLK H}	ns	0.45 × T _{CLK}	0.5 × T _{CLK}	0.55 × T _{CLK}	
Clock falling edge to data delay	t _{CLK D}	ns	13	0	49	

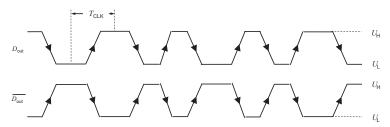
In mode 8, you can use external clock from 5 to 10.1 MHz or from 11.4 to 12.5 MHz.

Levels

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Low voltage	U_{L}	V			0.4	with $I_{\text{outL}} = 4 \text{ mA}$, unloaded
High voltage	U_{H}	V	<i>U</i> _c - 0.4			with $I_{\text{out H}} = -4 \text{ mA}$, unloaded



Mode 1: 2 Wire RS 422 Manchester (ANSI/TIA/EIA-422-B and IEEE 802.3)



For all allowed capacitive range, $R_{\rm L}$ can be 100 Ohm. Logical 1 is coding on a rising edge on $D_{\rm out}$.

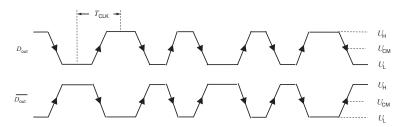
• Timing for mode 1

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock period	T_{CLK}	ns	89	93.5	98	f _{CLK} = 10.7 MHz ±5 %
Temperature coefficient of clock period	$TCt_{\mathrm{per\ CLK}}$	ppm/K	-400	0	400	−40 °C 105 °C

Levels

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Low voltage	U_{L}	V			0.4	with $I_{\text{out L}} = 4 \text{ mA}$, unloaded
High voltage	U_{H}	V	<i>U</i> _c − 0.4			with $I_{\text{out H}} = -4 \text{ mA}$, unloaded

Mode 3: 2 Wire LVDS Manchester (ANSI/TIA/EIA-644-A and IEEE 802.3)



For all allowed capacitive range, recommended load resistor $R_{\rm L}$ = 100 Ohm. Logical 1 is coding on a rising edge on $D_{\rm cut}$.

• Timing for mode 3

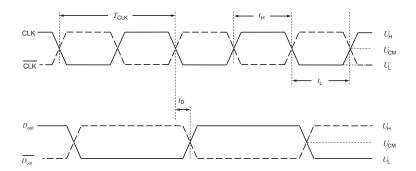
Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock period	T_{CLK}	ns	89	93.5	98	f _{CLK} = 10.7 MHz ±5 %
Temperature coefficient of clock period	TCt _{per CLK}	ppm/K	-400	0	400	−40 °C 105 °C

Levels

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Low voltage	U_{L}	mV		$(-3.5 \times R_{L}) / 2$		Relative to $U_{\text{\tiny CM}}$
High voltage	U_{H}	mV		(3.5 × R _L) / 2		Relative to $U_{\text{\tiny CM}}$
Common mode voltage	U_{CM}	V		1.25		



Mode 2 and A: 4 Wire LVDS (ANSI/TIA/EIA-644-A)



For all allowed capacitive range, recommended load resistor R_L = 100 Ohm.

• Timing for mode 2

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock period	T_{CLK}	ns	89	93.5	98	For internal clock
Temperature coefficient of clock period	TCt _{per CLK}	ppm/K	-400	0	400	−40 °C 105 °C
Clock high time	t _{CLK H}	ns	0.45 × T _{CLK}	46.75	0.55 × T _{CLK}	
Clock falling edge to data delay	t _{CLK D}	ns	-25	0	25	

• Timing for mode A

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock high time	t _{CLK H}	ns	0.45 × T _{CLK}	0.5 × T _{CLK}	0.55 × T _{CLK}	
Clock falling edge to data delay	t _{CLK D}	ns	13	0	49	

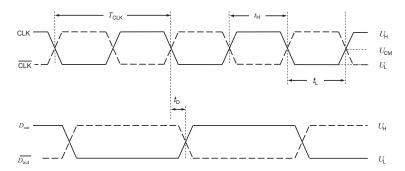
In mode A, you can use external clock from 5 to 10.1 MHz or from 11.4 to 12.5 MHz.

Levels

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Low voltage	U_{L}	mV		$(-3.5 \times R_{L}) / 2$		Relative to $U_{\rm CM}$
High voltage	U_{H}	mV		(3.5 × R _L) / 2		Relative to $U_{\rm CM}$
Common mode voltage	U_{CM}	V		1.25		



Mode 4, C and D: 4 Wire RS 422 (ANSI/TIA/EIA-422-B)



For all allowed capacitive range, $R_{\rm L}$ can be 100 Ohm.

• Timing for mode 4

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock period	T_{CLK}	ns	89	93.5	98	For internal clock
Temperature coefficient of clock period	$TCt_{per\;CLK}$	ppm/K	-400	0	400	−40 °C 105 °C
Clock high time	t _{CLK H}	ns	0.45 × T _{CLK}	46.75	0.55 × T _{CLK}	
Clock falling edge to data delay	t _{CLK D}	ns	-25	0	25	

• Timing for mode C and D

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Clock high time	t _{CLK H}	ns	0.45 × T _{CLK}	0.5 × T _{CLK}	0.55 × T _{CLK}	
Clock falling edge to data delay	t _{CLK D}	ns	13	0	49	

In mode C and D, you can use external clock from 5 to 10.1 MHz or from 11.4 to 12.5 MHz.

Levels

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Low voltage	U_{L}	٧			0.4	with $I_{\text{out L}} = 4 \text{ mA}$, unloaded
High voltage	$U_{\rm H}$	V	<i>U</i> _c − 0.4			with $I_{\text{out H}} = -4 \text{ mA}$, unloaded
Common mode voltage in mode C	U_{CM}	V	0.35 × U _c		0.75 × U _c	
Common mode voltage in mode D	U_{CM}	V		0		

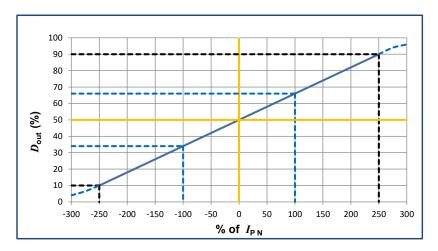
Mode D fully compatible with RS 422 standard (ANSI/TIA/EIA-422-B).

Capacitors on CLK and \overline{CLK} signals needed to avoid common mode voltage.

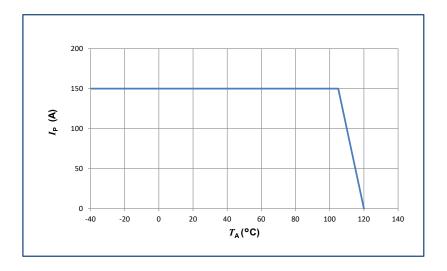


HO-NPW series output characteristics

Modulator output: Density of ones versus % of I_{PN}



Maximum continuous DC current



For all ranges:

Important notice: whatever the usage and/or application, the transducer primary bar / jumper temperature shall not go above the maximum rating of 120 °C as stated in page 2 of this datasheet.





HO-NPW series output characteristics

Consumption

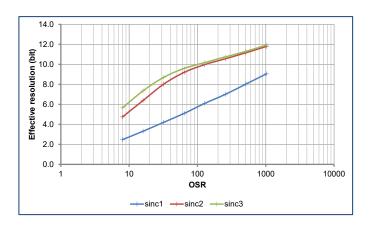
Typical values with $C_{\rm L}$ = 5 pF

Output Mode	I _c unloaded (mA)	$I_{\rm c}$ with $R_{\rm L}$ = 100 Ohm (mA)
0	24	-
1	24	53
2	-	37
3	-	30
4	25	82
8	24	-
Α	-	30
С	24	53
D	24	53

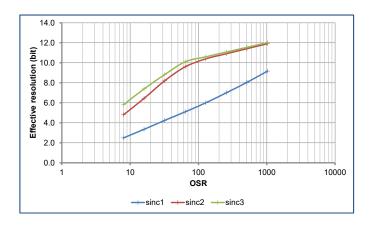


Effective resolution versus OSR

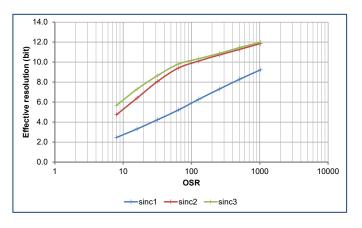
HO 80-NPW-xxxx



HO 120-NPW-xxxx



HO 150-NPW-xxxx

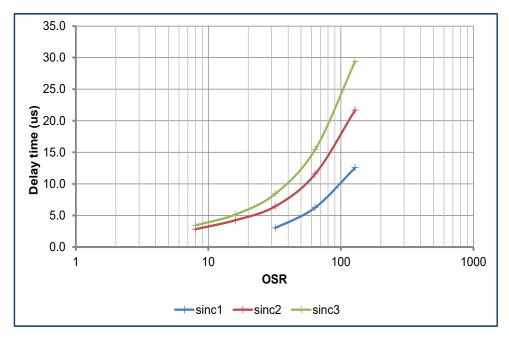


Signal to noise ratio

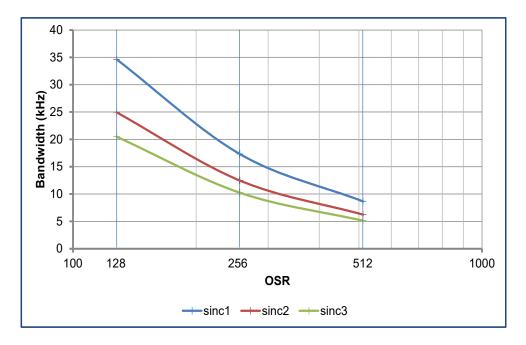
SNR (dB) = $20 \cdot \log_{10} (2)$ / Effective resolution



Delay time versus OSR



Bandwidth (-3 dB) versus OSR

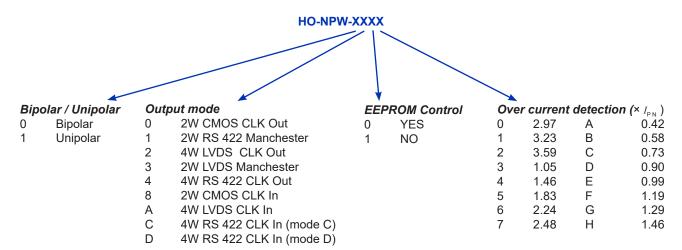


Theoretical values due to customer filter configuration



HO-NPW series: name and codification

HO-NPW family products may be ordered **on request** 1) with a dedicated setting of the parameters as described below (standards products are delivered with the setting 0000 according to the table).



Standard products are:

Other products available:

HO 80-NPW-0000 HO 120-NPW-0000 HO 150-NPW-0000	HO 80-NPW-0100 HO 120-NPW-0100 HO 150-NPW-0100	HO 80-NPW-0800 HO 120-NPW-0800 HO 150-NPW-0800
	HO 80-NPW-0200 HO 120-NPW-0200 HO 150-NPW-0200	HO 80-NPW-0A00 HO 120-NPW-0A00 HO 150-NPW-0A00
	HO 80-NPW-0300 HO 120-NPW-0300 HO 150-NPW-0300	HO 80-NPW-0C00 HO 120-NPW-0C00 HO 150-NPW-0C00
	HO 80-NPW-0400 HO 120-NPW-0400 HO 150-NPW-0400	HO 80-NPW-0D00 HO 120-NPW-0D00 HO 150-NPW-0D00

Note: 1) For dedicated settings, minimum quantities apply, please contact your local LEM support.



Application information

Possibilities between range selection and number of turns 1) and 2

Number of primary turns	Primary current					
Number of primary turns	I _{PN} = 80 A	I _{PN} = 120 A	I _{PN} = 150 A			
1	80 A	120 A	150 A			
2	40 A	60 A	75 A			
4	20 A	30 A	37.5			

Connection diagram

Number of primary turns	Primary resistance current RMS R_p [m Ω] @ T_A = 25 °C	Recommended connections
1	0.09	OUT 13 14 15 16
		12 11 10 9 IN
2	0.36	OUT 13 14 15 16
		12 11 10 9 IN
		OUT 13 14 15 16
4	1.44	
		12 11 10 9 IN

Notes: 1) The standard configuration is with all jumpers in parallel (1 primary turn) which is the only one calibrated and guaranteed by LEM. The sensitivity may change slightly for all other configuration, therefore, LEM advises the user to characterize any specific configuration.

Remark

Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: https://www.lem.com/en/file/3137/download/

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary busbar, power supply). Ignoring this warning can lead to injury and/or cause serious damage. This transducer is a build-in device, whose conducting parts must be inaccessible after installation. A protective housing or additional shield could be used. Main supply must be able to be disconnected.

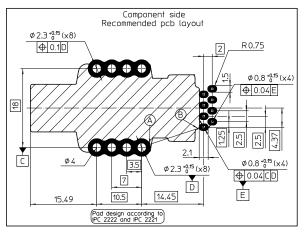
Although LEM applies utmost care to facilitate compliance of end products with applicable regulations during LEM product design, use of this part may need additional measures on the application side for compliance with regulations regarding EMC and protection against electric shock. Therefore LEM cannot be held liable for any potential hazards, damages, injuries or loss of life resulting from the use of this product.

²⁾ The maximum magnetic offset referred to primary is inversely proportional to the number of turns, thus is divided by 2 with 2 turns and by 4 with 4 turns.



PCB Footprint in mm

(Layout example with 4 jumpers in parallel)



Assembly on PCB

- Recommended PCB hole diameter
- Maximum PCB thickness
- Wave soldering profile No clean process only

2.15 mm for primary pin 0.8 mm for secondary pin

2.4 mm

maximum 260 °C, 10 s

Insulation distance (nominal values):

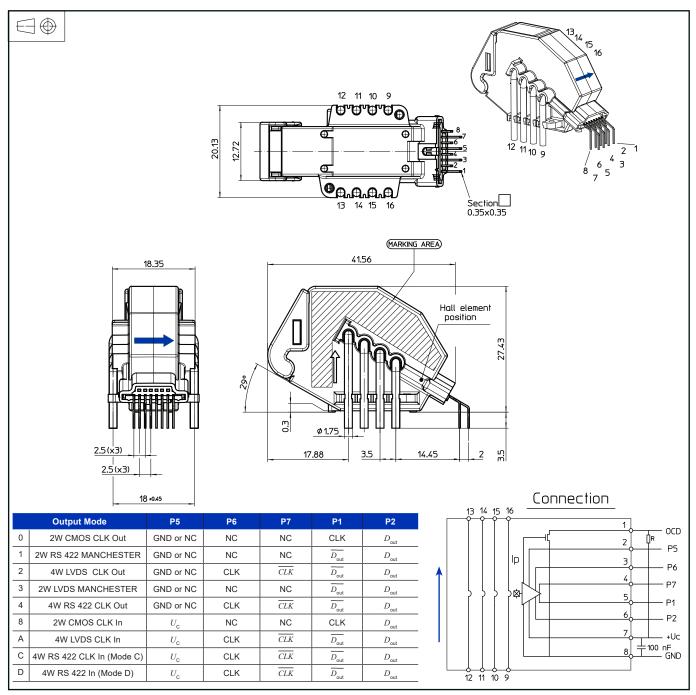
	$d_{\sf Cp}$	d _{Cl}
On PCB: A - B	11.83 mm	-
Between jumper and secondary pin	-	13.08 mm
Between core and PCBA	13.56 mm	8.05 mm

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution. Typical, minimum and maximum values are determined during the initial characterization of the product.



Dimensions (in mm, general linear tolerance ±0.6 mm)



Remark:

• Density of ones is greater than 50 % when positive I_p flows in direction of the arrow shown on the drawing above.





Mounting recommendation

Recommendation for manual mounting:
- Special care has to be taken during insertion to avoid any deformation or violent bending.
It is recommended to start with the insertion of the secondary pins (1).
Then the primary pins (2) can be aligned with their mounting holes and the insertion process be easily completed.

Automatic insertion is not recommended for this product or may require special jigs.

